

# FLYBOX®



**RPM-MAP**  
*(Omnia57 family)*

**Installation and User Manual, Safety  
Instructions and Warning Booklet**

**This product is not TSO'd and cannot be installed into  
traditional FAA Part 23 and similarly Type-Certificate Aircraft**

Document A2019RPM-MAP  
Revision#1.0, 02/2019  
For firmware version 1.0

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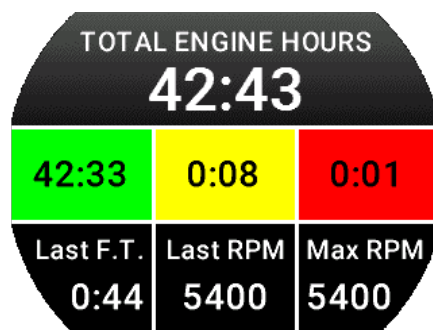
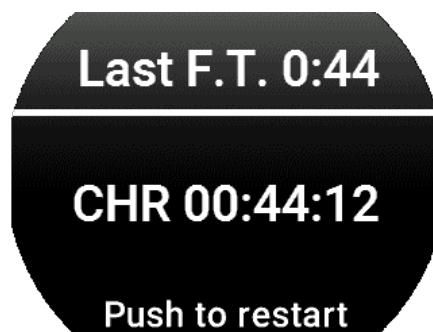
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Thank you for purchasing a Flybox® **Omnia57** instrument.

Our intent in developing the **Omnia57** instrument family was to create a light and compact product, powerful and easy to install and use.

The **Omnia57** instrument family is equipped with a state-of-the-art highly visible display, a powerful 32 bit microcontroller and the latest generation of solid state sensors to ensure reliability and accuracy over time.

The owner has the possibility to keep the instrument software up-to-date by downloading the latest available revision from the [www.flyboxavionics.it](http://www.flyboxavionics.it) website and installing it using a USB pen drive.

We are confident our products will be satisfactory and will make your flying experience a pleasant one.

### **Symbols used in the Installation and User Manual, Safety Instructions and Warning Booklet**



**NOTE:** Used to highlight important information.

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**CAUTION:** Used to warn the user, it indicates a potentially hazardous situation or improper use of the product.

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**WARNING:** Used to indicate a dangerous situation that can cause personal injury or death if the instruction is disregarded.



**WARNING:** These instructions must be provided to users before use, and retained for ready reference by the user. The user must read, understand (or have explained) and heed all instructions and warnings supplied with this product and with those products intended for use in association with it. Always keep a copy of the Installation and User Manual, Safety Instructions and Warning Booklet on the aircraft. In case of change of ownership, the Installation and User Manual, Safety Instructions and Warning Booklet must be delivered together with all of the other papers.

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**WARNING:** Read the Installation and User Manual, Safety Instructions and Warning Booklet before installing the device on your aircraft and follow the procedure described therein.

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**WARNING:** This device is intended to be installed on NON-TYPE CERTIFIED AIRCRAFT ONLY, as it does NOT require any air operator's certificate. Refer to your national aviation authorities to check if this device can be installed on your aircraft.

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**WARNING:** It is the owner's responsibility to test this device before operating the aircraft and to make sure nobody is using it unless properly instructed and authorized to do so.

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**WARNING:** Once the installation process is completed, it is extremely important to test the device before taking off to make sure it works properly. Therefore, we strongly suggest to double check all of the electronic instruments available on the aircraft and to turn them on to verify they function correctly.



**WARNING:** This device is operated through a software which from time to time can be updated and/or subject to change. Please, always refer to the Installation and User Manual, Safety Instructions and Warning Booklet for the last updated version of the software available at [www.flyboxavionics.it](http://www.flyboxavionics.it)

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**WARNING:** It is the responsibility of the installer to properly install the device on the aircraft. In case of calibration, or any technical or functional customization of the device, the responsibility lies with the individual who carried out such operation.

FAILURE TO DO SO MAY RESULT IN SERIOUS INJURY  
OR DEATH.

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**WARNING:** If this product is not used correctly, or it is subjected to additions or alterations, the effectiveness of this device may be considerably reduced.

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**WARNING:** Alterations, additions, or repairs not performed by the instrument manufacturer or by a person or organization authorized by the manufacturer shall negate any warranty.

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**WARNING:** Do NOT rely on the Omnia57 Fuel L-P device ONLY to determine the level of the fuel available in the tanks.

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**WARNING:** The unit isn't waterproof. Serious damage could occur if the unit is exposed to water or spray jets.





**NOTE:** The consumer decides of his own free will if the purchased product is suitable and safe for his need. If the consumer does not agree with the notices contained in this Installation and user Manual, Safety Instructions and Warning Booklet, do not install this instrument in his aircraft.

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**NOTE:** Flybox Avionics reserves the right to change or improve its products as well as terms, conditions, and notices under which their products are offered without prior notice.

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**NOTE:** The Installation and User Manual, Safety Instructions and Warning Booklet will be updated annually if needed.

All changes or updates will be published on our website [www.flyboxavionics.com](http://www.flyboxavionics.com) in the "support" section.

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**NOTE:** Upon receipt of the instrument it is advisable to register on our website [www.flyboxavionics.it](http://www.flyboxavionics.it) in the "product registration" section.

The Registration data will be used only to send important news or information about available firmware updates or to communicate safety information about the instrument.

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## **OMNIA57 FAMILY SYSTEM OVERVIEW**

The **Omnia57** instrument family has many innovative features, common to all models as described below.

### **1.1 CONSTRUCTION FEATURES**

**Omnia57** instrument family is built from solid aluminum alloy, CNC milled and powder coated to last a long time over the years always showing a new appearance.

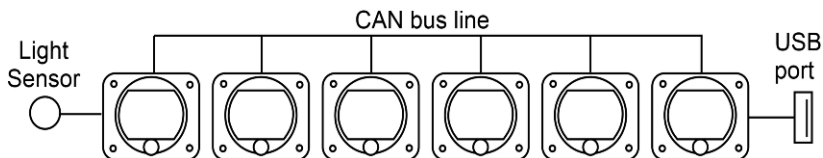
### **1.2 ERGONOMICS**

- Large 2.4 inch TFT display, 320x240 Pixels, 1000 nits, antiglare surface, sunlight readable, wide temperature range.
- A high quality knob encoder with push button for easy access to all features.
- Backlight auto dimming feature with one optional sensor for all the Omnia57 installed in the panel.

### **1.3 INTERCONNECTION ABILITY**

All the instruments of the **Omnia57** family can be connected together to form a communication network, making some data exchange operations simpler.

The software update of a **Omnia57** instrument connected in group takes place through the CAN bus communication with the instrument that has the USB pen drive connected. This means that the USB connection is made to a single instrument, and the information will be forwarded via CAN bus to or from all the others in the group.



Up to 16 Omnia57 can be connected together through the CAN 1 bus.

The configuration data and the data logger of the interconnected instruments are saved or restored via CAN bus on the same USB pen drive. A single brightness sensor can provide information to all the connected instruments to automatically adjust the backlight intensity.

## **1.4 EASY SOFTWARE UPDATE**

The user can download any new firmware, when available, from Flybox website, connect a USB pen drive to the instrument and freely update it with the last features.

With one USB connection only, it will be possible to update every instrument installed in the panel. If more Omnia57 are installed and properly connected, they will search for the right firmware through the CAN bus.

## **1.5 EASY DATALOG SAVING**

Easy logging of the data for debug purpose. If needed, each **Omnia57** unit can save a last flight log on the USB pen drive. The user can then send the log via e-mail to Flybox support for a help/support request.

## 1.6 INTERFACES

All the **Omnia57** instruments have the following common interfaces:

**2 separate CAN BUS:** they can be used to connect the **Omnia57** instruments together, to interface them with other Flybox instruments or with external devices like Engines ECUs or new devices that will be possible developed in the future.

**2 RS232 serial ports:** used to connect the **Omnia57** instruments to an external GPS (when applicable). This feature appears in some models only.

**1 Sensor Light Input:** if connected, it allows the automatic light intensity adjustment, one sensor for all the instruments.

**2 Power outputs for sensors:** one 12 V 500mA@60°C and the other 5 V 350 mA@60°C, both protected from short circuit.

If the current on one of the outputs is too high, a caution message will appear.

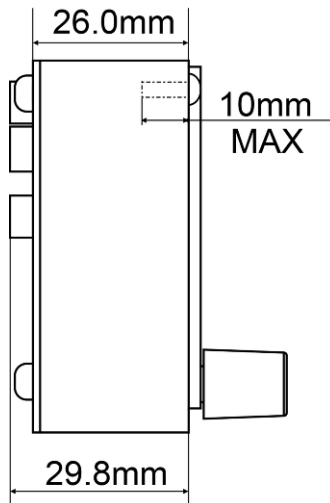
**Caution!**  
High current PIN 2

**1 Alarm output:** all the **Omnia57** instruments can activate an external warning device like a lamp or a small relay through this NPN transistor output.

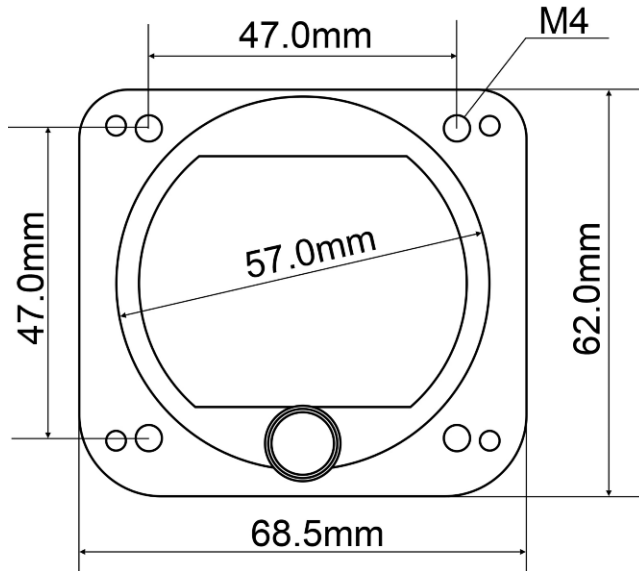
## **MECHANICAL INSTALLATION**

### **2.1 MECHANICAL DIMENSIONS**

The **Omnia57 RPM-MAP** instrument fits in a standard 2 1/4" (57 mm) panel cutout; it's recommended to choose a position that permits optimal display visibility. It's furnished with four M4 screws to install it to the panel, if you use other screws consider that the maximum thread length inside the instrument body is 10mm (see the picture below).



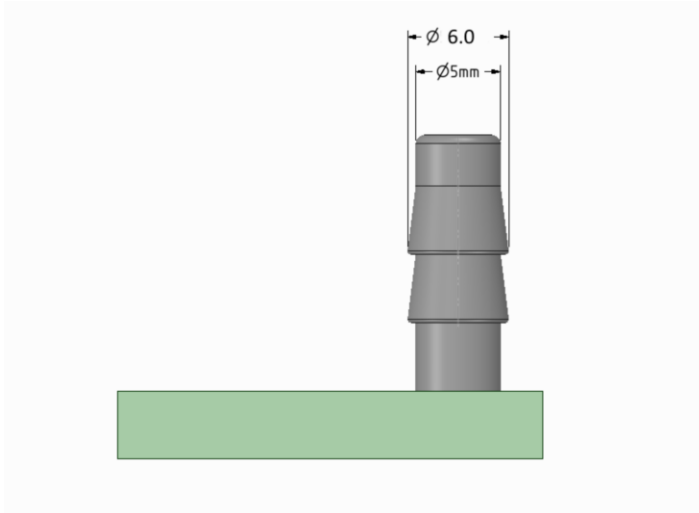




**NOTE:** For an installation without interference, consider making a hole of at least 57.5 mm diameter

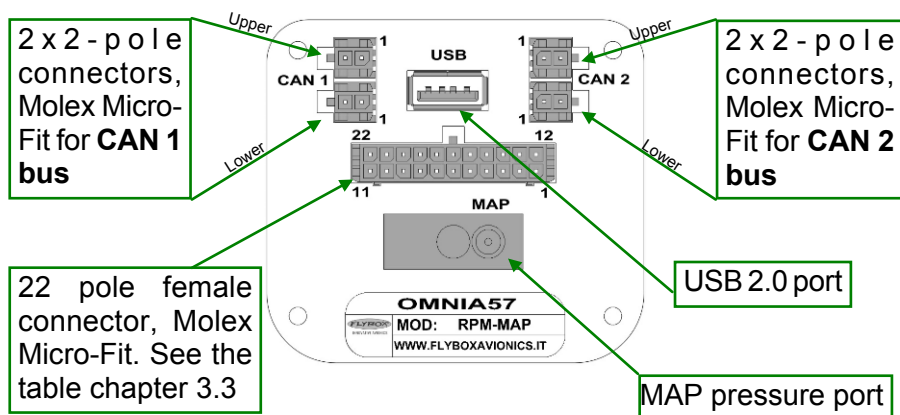
## 2.2 MAP PIPING CONNECTION

On the back of the instrument there is a 6mm brass fitting that must be connected and tightened to the fitting of the engine by a rubber tube.



## ELECTRICAL INSTALLATION

### 3.1 REAR PANEL CONNECTIONS



The required connectors and terminals are supplied with the instrument.

The manufacturer's codes are:

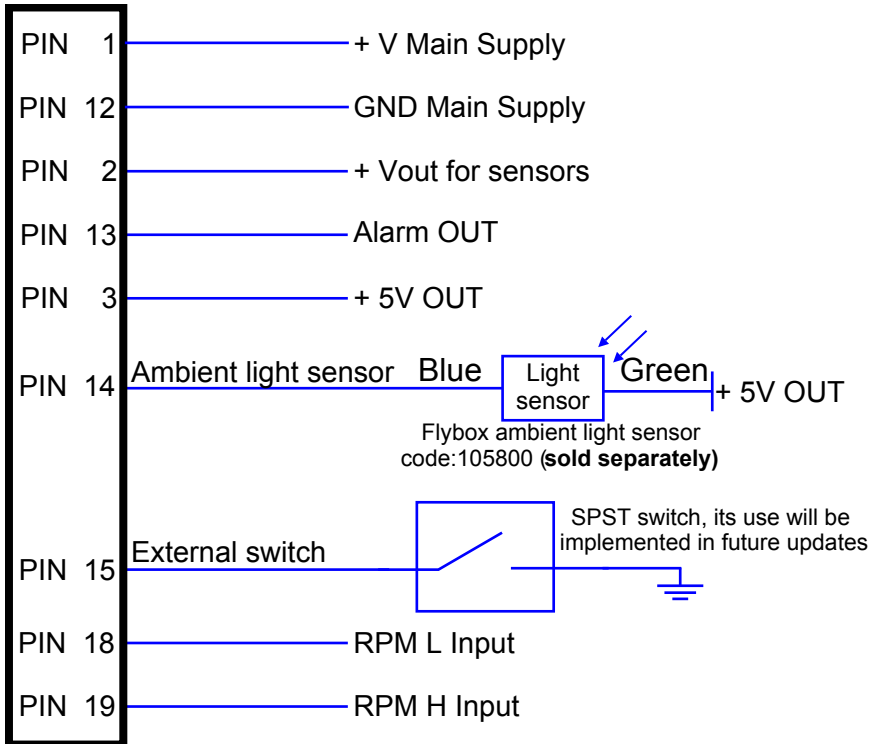
- Molex P/N 43025-0200 (2 pole housing)
- Molex P/N 43025-2200 (22 pole housing)
- Molex P/N 43030-0007 (female crimp terminal)

The terminals can be crimped with:

- Flybox Professional Crimping Tool cod. 603000
- Molex tool P/N 63819-0000

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Safety Instructions and Warning Booklet

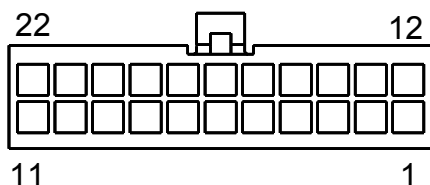
### 3.2 - (22 POLE) FEMALE CONNECTOR WIRING



**⚠ WARNING:** Voltage peaks on the supply line exceeding the operating limits can damage the device.

### 3.3 - (22 POLE) CONNECTOR TABLE

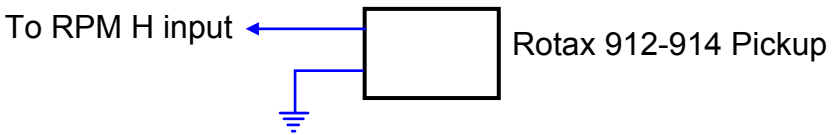
PIN	I/O	Signal
1	I	+V Main supply, 10-30Vdc, with a proper breaker
2	O	Vout for sensors, it delivers the same voltage supplied on the Pin 1, short circuit protected and limited to 500mA
3	O	5V out for sensor, short circuit protected and limited to 350mA
12	I	GND main supply
13	O	Alarm Out, NPN 300 mA (not protected)
14	I	Ambient light sensor input
15	I	External switch
18	I	RPM L Input (2-20Vpp min 100uS)
19	I	RPM H Input (5-100Vpp min 100uS)



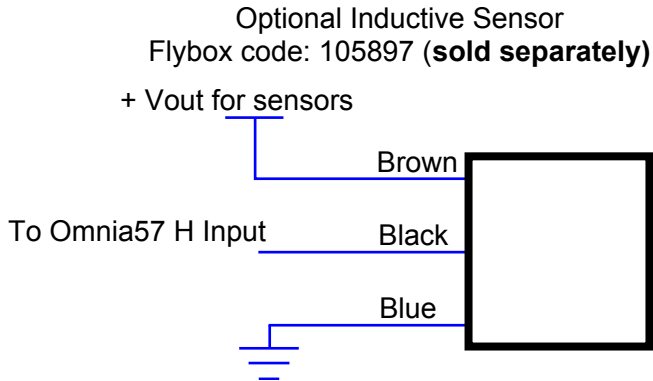
Molex P/N 43025-2200 (22 pole housing). View from wire insertion side.

## 3.4 SENSORS ELECTRICAL CONNECTIONS

### 3.4.1 Rotax Revolution Counter Pickup




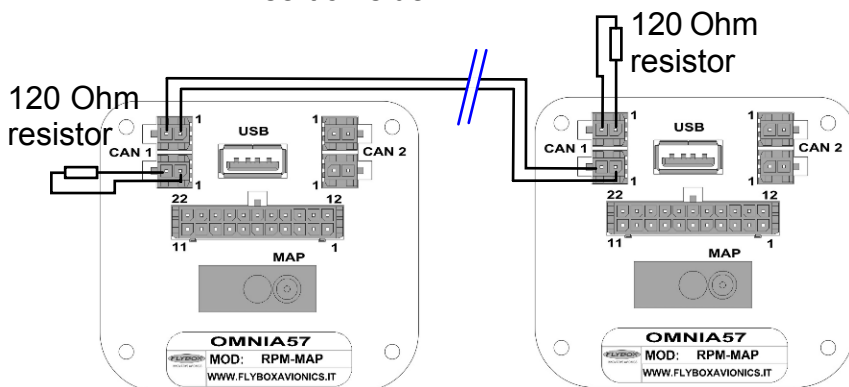
### 3.4.2 Flybox Inductive Pickup



**NOTE:** for different needs, please contact Flybox support.

### 3.5 CAN BUS CONNECTION WIRING

Pin 2  Molex P/N 43025-0200 (2 pole housing). View from wire insertion side  
 Pin 1



### CAN bus Wiring Information

The basic electrical architecture of a CAN bus consists of a single twisted or shielded wire pair with a device connected at each end. Each end must be terminated with a 120 ohm resistor, Flybox code 105810. Up to 16 Omnia57 can be connected together through CAN 1 bus. Ready-made termination resistors and wiring for connecting several Omnia57 together are available in different lengths: 25cm, 50cm, 100cm.

See the website [www.flyboxavionics.it](http://www.flyboxavionics.it) for details and how to order.

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### 3.6 - (2 POLE) CAN BUS CONNECTOR TABLES

PIN	I/O	Signal
1	I/O	<b>CAN 1 H</b> Internally connected with the Pin 1-CAN 1 H (Lower connector)
2	I/O	<b>CAN 1 L</b> Internally connected with the Pin 2-CAN 1 L (Lower connector)

#### 2 Pole **CAN 1** Lower Connector

PIN	I/O	Signal
1	I/O	<b>CAN 1 H</b> Internally connected with the Pin 1-CAN 1 H (Upper connector)
2	I/O	<b>CAN 1 L</b> Internally connected with the Pin 2-CAN 1 L (Upper connector)

#### 2 Pole **CAN 2** Upper Connector

PIN	I/O	Signal
1	I/O	<b>CAN 2 L</b> Internally connected with the Pin 1 CAN 2 L (Lower connector)
2	I/O	<b>CAN 2 H</b> Internally connected with the Pin 2 CAN 2 H (Lower connector)

#### 2 Pole **CAN 2** Lower Connector

PIN	I/O	Signal
1	I/O	<b>CAN 2 L</b> Internally connected with the Pin 1 CAN 2 L (Upper connector)
2	I/O	<b>CAN 2 H</b> Internally connected with the Pin 2 CAN 2 H (Upper connector)



## INSTRUMENT SETTINGS

### 4.1 MINIMUM SETTINGS BEFORE FIRST USE



**CAUTION:** Before using the **Omnia57 RPM-MAP** in flight for the first time, you must set at least the following parameters (as explained in the instructions on the following pages):

- Set the engine type.
- Set all the parameters contained in the RPM Submenu including the Alarm parameters.
- Set all the parameters contained in the MAP Submenu.
- Check if the indications are correct for all the gauges.



**WARNING:** In the absence of the above operations, or if they are not performed correctly, you can not consider as reliable the indications of the instrument.

## 4.2 PANEL INDICATORS & COMMANDS



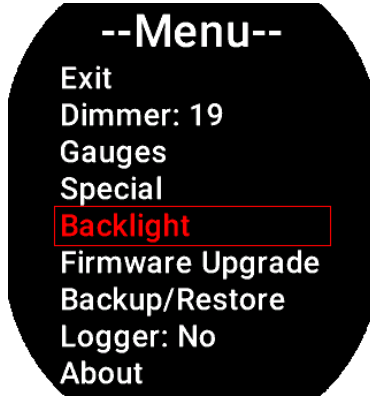
The knob can be rotated to select the functions and increment or decrement the values while pressing it to confirm.

## **4.3 SETUP MENU NAVIGATION**

Navigation through the menus is very simple and fast using the knob:

- Press the knob for 1 second to enter in the Setup Menu. The menu automatically disappears if you don't press or rotate the knob for 5 seconds.
- Rotate the knob to navigate through menus and submenus items.
- The setup system is organized in menus and submenus; a submenu is a term used to describe a menu that is contained within another menu.
- Press the knob to enter in the selected item.
- The knob can be rotated to select the functions and increment or decrement the values while pressing it to confirm. To exit without changing while editing a number or multiple choice, keep pressed the knob for 3 seconds.
- The first items on every menu are Exit or Back. "Exit" is used to quit the Setup and go directly to the main screen, "Back" is used to go back to the previous level.

## 4.4 MAIN SETUP MENU

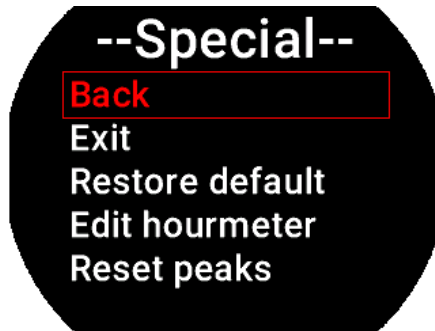


**Exit:** confirm to “exit” from the setup menu and go back to the main screen.

**Dimmer:** adjust display brightness from 1 (min brightness) to 19 (max brightness). Default value=19. The adjustment works both in Manual or in Automatic mode.

**Gauges:** select to set the RPM and the MAP gauge setup. Go to chapter **4.4.1** for a full description.

**Special:** enter to restore the default settings, to edit the hourmeters or to reset RPM peaks.



**Back:** confirm to go back to previous menu.

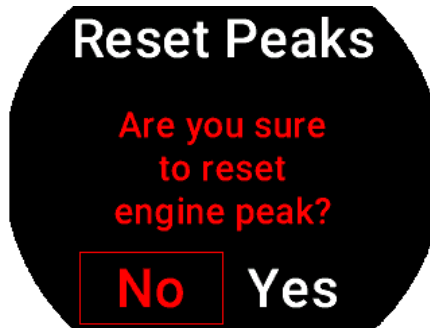
**Exit:** confirm to go directly to the main screen.

**Restore Defaults:** enter to restore defaults. **Caution**, the restore default operation returns the instrument to the factory settings. **It will require double confirmation.**

**Edit hourmeter:** enter to edit the 3 hobbs meter. Select the green, the yellow or the red meter and click to edit it. Rotate the knob to change the value and push to confirm. When done exit with a long press.



**Reset Peaks:** enter to reset the RPM peak.



Select “Yes” to reset the RPM peak. This operation will require a double confirmation.

**Backlight:** set the backlight in “Manual” or “Automatic” mode. Go to chapter **4.5** for a full description.

**Firmware Upgrade:** enter to upgrade the firmware. Go to chapter **5.1** for a full description.

**Backup/Restore:** enter to save and load settings. Go to chapter **5.2** for a full description.

**Logger:** enable to save a flight session data. Go to chapter **5.4** for a full description.

**About:** enter to see instrument information.



About Page Example

### 4.4.1 Gauges Submenu



**Back:** confirm to go back to previous menu.

**Exit:** confirm to go directly to the main screen.

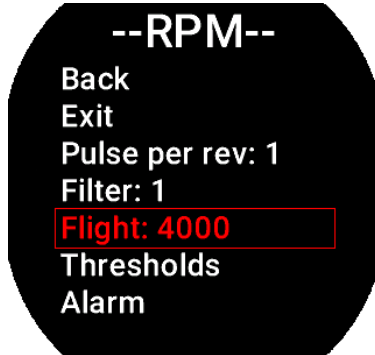
**Eng:** choose the type of engine from: Lycoming, Continental, Rotax 912, Rotax, 914, Rotax 912iS, Rotax 915 iS. If your engine is not in the list, choose “Other”.

**RPM:** enter to setup the Tachometer parameters. Go to chapter 4.4.2 for a full description.

**MAP:** enter to setup the MAP parameters. Go to chapter 4.4.3 for a full description.



## 4.4.2 RPM Submenu



**Back:** confirm to go back to previous menu.

**Exit:** confirm to go directly to the main screen.

**Pulse per rev:** enter the pulse per revolution of your engine. Check the documentation of your engine to know how many pulses per revolution it delivers.

Default = 1

Min = 1

Max = 200

**Filter:** set the fluctuation speed of the RPM readings.

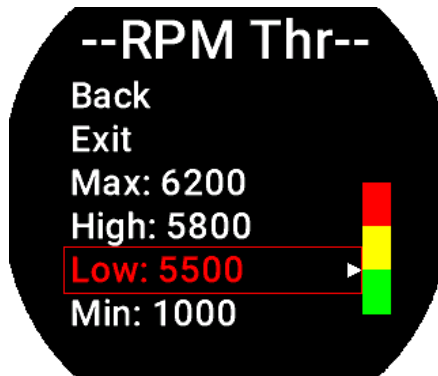
Default = 1

Min = 1 (faster)

Max = 10 (slower)

**Flight:** set the RPM required to start the flight timer (the flight timer starts automatically when the engine's RPM meets or exceeds this parameter for 30 seconds). Range:0~10000, default=4000.

**Thresholds:** set all the thresholds for the RPM gauge.



Rotate the knob to highlight the threshold you want to change, push and change the value, push again to confirm. Default thresholds are at 0.

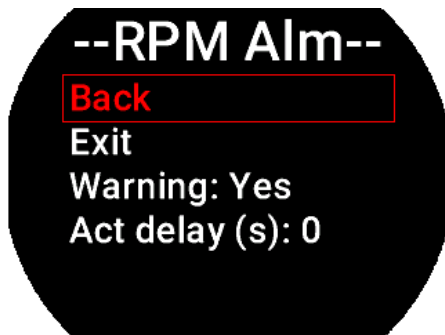


**NOTE:** Start to change the maximum thresholds and then, gradually, the lower thresholds.



**NOTE:** To make a colored portion disappear, give the same value to the low and high thresholds of that color.

**Alarms:** enter to go in the RPM Alarm menu.



**Back:** go back to previous menu.

**Exit:** confirm to go directly to the main screen.

**Warning:** select “Yes” to enable or select “No” to disable the alarm output.

**Act delay:** Select a delay in seconds before the alarm is triggered. When the threshold is reached, the alarm output will be activated after the set time. This option can be useful to avoid continuous alarms when the measure is stationary at values close to the set threshold.

Default = 0s

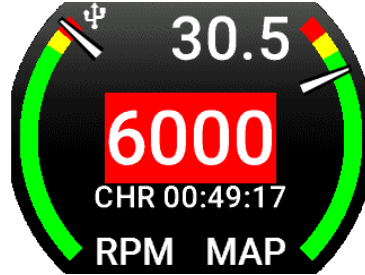
Min = 0s (faster)

Max =10s (slower)

The alarm is only triggered if the Warning parameter is set to "Yes". The alarm event triggers both the flashing message on the screen and the alarm output. Both of them can be reset by pressing the knob but the rectangle behind number remains in red. Both of them clear themselves when the RPM returns below the alarm threshold.



Before resetting



After resetting with the knob



When the RPMs are in yellow arc, a yellow rectangle appears below the numbers.

### 4.4.3 MAP Submenu



**Back:** go back to previous menu.

**Exit:** confirm to go directly to the main screen.

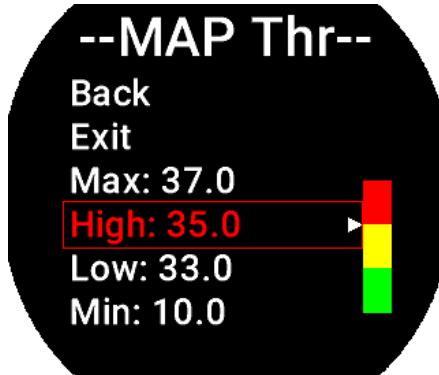
**Filter:** set the fluctuation speed of the MAP readings.

Default = 10

Min = 1 (faster)

Max = 100 (slower)

**Thresholds:** set all the thresholds for the MAP gauge.



Rotate the knob to highlight the threshold you want to change, push and change the value, push again to confirm. Default thresholds are at 0.



**NOTE:** Start to change the maximum thresholds and then, gradually, the lower thresholds.



**NOTE:** To make a colored portion disappear, give the same value to the low and high thresholds of that color.

## 4.5 Backlight Submenu

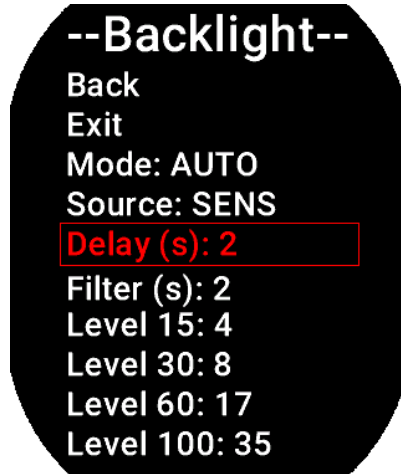


**Back:** go back to previous menu.

**Exit:** confirm to go directly to the main screen.

**Mode:** select to choose from “Manual” and “Auto”. When in “Manual” mode, the brightness can be changed with the dimmer function from the main menu, from 1 (min brightness) to 19 (max brightness). Default value=19. Selecting “Auto” new parameters will appear in the list:

**Source:** set how the instrument reads the ambient brightness. Choose "Sens" to read the brightness from the sensor connected to the instrument itself or "CAN" to read the ambient brightness from the CAN bus if the brightness sensor is connected to another Omnia57 instrument connected in cluster.



**Delay (s):** It introduces a delay to the variation of the backlight, it can be useful to avoid continuous changes in brightness when the sensor is hit by light and shadow alternately.

Default= 2 s  
Min= 0 s (faster)  
Max= 10 s (slower)

**Filter (s):** The filter slows down the response to changes in external brightness, it raises the value to slow down, lower it to speed them up.

Default = 2 s  
Min = 0 s (faster)  
Max 30 s (slower)



This function assigns the amount of light read by the sensor to the target brightness (Level 15 = 15% brightness).

Once all 4 points have an assigned value, the brightness will change according to the amount of light read, interpolating it between the segments that are created.

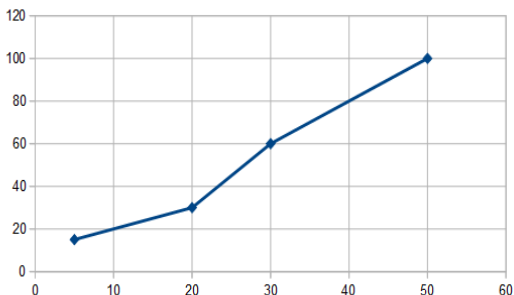
**Level 15: 4**

**Level 30: 8**

**Level 60: 17**

**Level 100: 35**

Defaults values



## OPERATING INSTRUCTIONS

### 5.1 FIRMWARE UPGRADE

The Omnia57 RPM-MAP software can be easily updated with new versions, when available. To check if a new software version is available, see [www.flyboxavionics.it](http://www.flyboxavionics.it) under support > software page.

Download the new version and after unpacking it, copy it to a USB stick, possibly free from other files.

To update the instrument it is necessary to connect the USB stick to the instrument you want to update or to any other instrument of the Omnia57 series installed and clustered via the CAN bus, following the procedure below:

- connect the usb stick to the instrument
- From the main menu of the instrument you want to upgrade select “Firmware Upgrade”.

If the USB stick is not yet plugged-in, a message advising you to insert it will appear:



If already plugged-in, a message indicating the file and the version will appear:



Select and confirm the software you want to write, the following screen will appear:



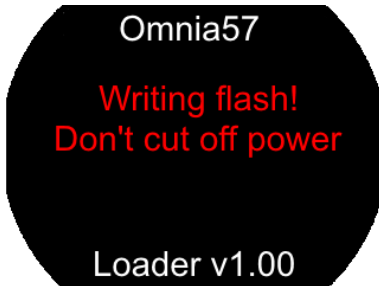
In case you are installing a version prior to the installed one, a different message will inform that you are **downgrading** and not upgrading the software. Confirm “Yes” to proceed, “No” to exit without writing any software.

(DEV. NAME) is the name of the instrument being update.

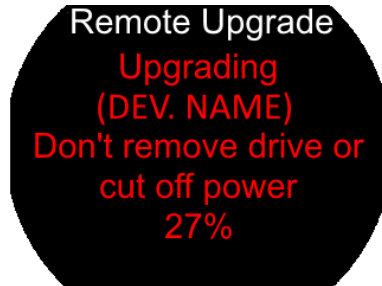
Wait until this message will appear and then remove the USB stick. The instrument will reboot with the new software.



**Note:** if the USB stick is installed on a device other than the one you are updating, the following messages will appear on the 2 devices:



Device is being Update



Remote device where the USB is connected

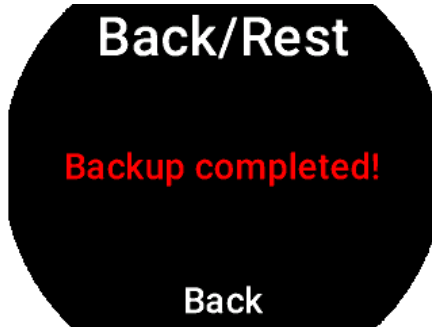
## 5.2 Backup / Restore

All set parameters and calibrations made in the instrument can be saved in a backup file. This can be useful if you need to restore all the parameters in a new instrument, for example in case of replacement, or if you need help from the instrument manufacturer. In this case, simply send the backup file saved on the USB stick to the Flybox support service. To backup or restore the parameters it is necessary to connect a USB stick to the instrument you want to backup/restore or to any other instrument of the Omnia57 series installed and clustered via the CAN bus.

From the main menu of the instrument you want to backup or restore the parameters, choose “Backup/Restore”. If the USB stick is not plugged-in yet, a message advising you to insert it will appear



Select “Backup” and push the knob to write the file on the USB stick. When the file is written, this message will appear:



Select “Restore” and push the knob to load the previously saved parameters into the instrument.



Push the knob to reboot, the new parameters are now loaded in the instrument.

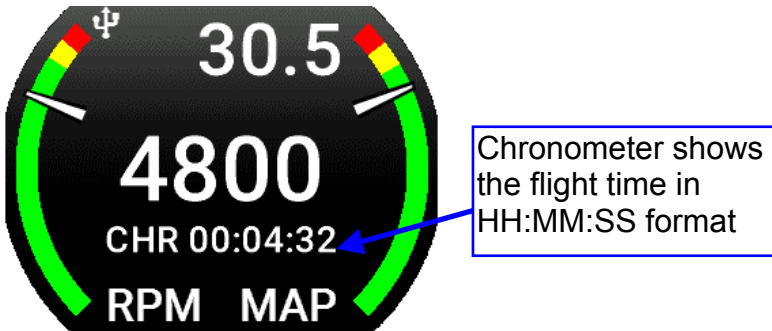
### 5.3 USE OF THE INSTRUMENT

When switched-ON, the display will immediately show the main screen.



Turn the knob to right and left to navigate through the pages.

### 5.3.1 Main page



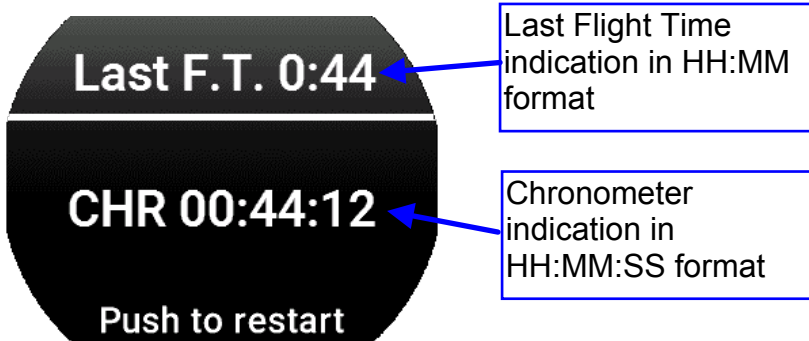
Here are shown the RPM and the MAP values.

An automatic chronometer starts when the take off is recognized, go to chapter **4.4.2** > “Flight” parameter for a full description.

Turning the knob to the right will show the Chronometer page.



### 5.3.2 Chronometer page



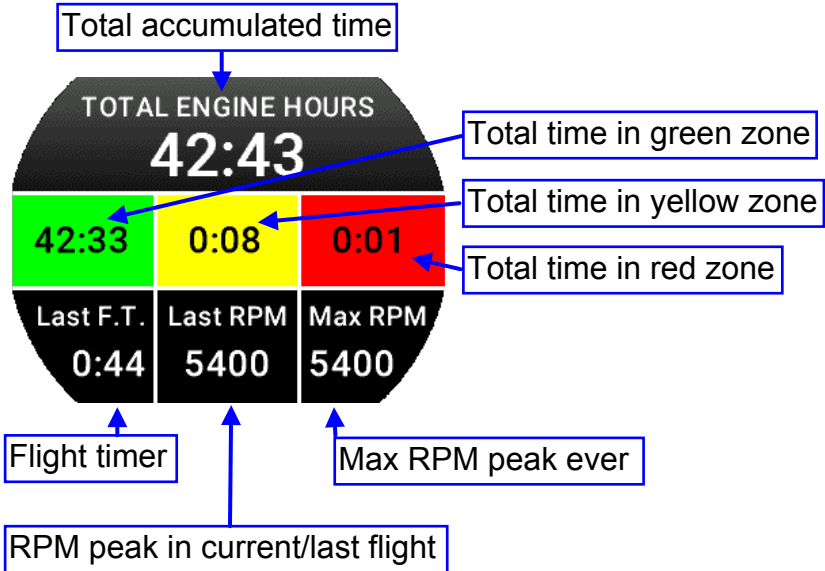
Push the knob to restart the Chronometer. This feature is useful to restart the chronometer with a simple click when you arrive at the waypoint. The Chronometer screen automatically disappears if you don't press or rotate the knob for 5 seconds. As soon as you press it, you return to the main screen.

The Chronometer indication is visible in the main screen too.

In the top of the screen there is the flight timer that starts automatically when the engine meets or exceeds for 30 seconds the value set in the "Flight" parameter, see chapter 4.4.2.

Turning the knob to the right will show the Hobbs meters page.

### 5.3.3 Hobbs Meter page



The information available on this page are:

**Total Engine Hours:** Total time accumulated by the engine. This time is further divided in total time accumulated in **green**, **yellow** and **red** zones.

**Last F.T.:** Last Flight Time. The flight timer starts automatically when the engine meets or exceeds for 30 seconds the value set in the “Flight” parameter, see chapter 4.4.2 > “Flight” parameter and it stops automatically when the engine is turned off (0000 RPM).

**Last RPM:** RPM Peak in current/last flight. Maximum RPM peak reached by the engine in the current flight (if you are in fly) or in the last flight (if you are grounded); it remains stored in memory until you begin a new flight.

**Max RPM:** Max RPM peak ever. Maximum peak RPM reached by the engine during its life.

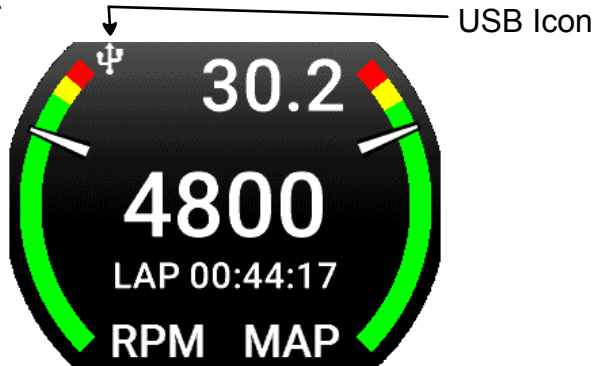
**NOTE:** All the hobbs meters data can be edited, it may be necessary, for example, when replacing the engine or when moving the instrument to another airplane.

### 5.4 Logger

The Logger can be useful for storing flight data on the USB stick, for example to ask for assistance in case of problems.

The data will be stored at 1 second samples and written on a file with some information of the instrument that generated them.

When the USB flash drive is plugged-in to the device to be logged or to any other instrument of the Omnia57 series installed and clustered via the CAN bus, a white icon will appear on the display indicating that the flash drive is connected.



To activate the Logger choose “Yes” from the Main Menu>Logger. The icon will turn **green** when the file is being written and **red** when the Logger is enabled but the USB stick is not connected.

## **TECHNICAL SPECIFICATIONS**

- Graphic TFT LCD with backlight and coated glass, dimensions 29x18mm.
- Standard mounting 2 1/4" (57mm).
- Powder painted aluminium case.
- Dimensions: 60 x 60 x 40 mm.
- Weight: 140g.
- Supply voltage: 10 ~ 30 V=.
- Supply current: 60mA.
- Open-collector alarm output (max 300mA, active low). This output can also be used to send a tone in the intercom, using the Flybox optional device code 105899.
- 2 inputs for RPM (high and low)
- 1 MAP port with internal sensor: 0-60 inHg
- Operating temperature range: -20 ~ +70°C.
- Humidity: 90% max (without condensation).
- Communication through 2 CAN bus.
- USB port: for USB 2.0

## **CLEANING**

The screen is very sensitive to some cleaning materials and should be cleaned with a clean, damp cloth only.

## **One Year Warranty:**

Product support and warranty information can be found at [www.flyboxavionics.it](http://www.flyboxavionics.it).

**Flybox®** warrants this Product to be free from defects in materials and workmanship for 12 months from date of delivery. The inactivity of the Products determined by periods of repair does not involve the extension of the warranty period.

This warranty covers only defects in material and workmanship found in the products under normal use and service when the product has been properly installed and maintained. This warranty does not cover failures due to abuse, misuse, accident, improper maintenance, failures to follow improper instructions or due to unauthorized alterations or repairs or use with equipments with which the Products is not intended to be used. Flybox®, after verification of the complaint and confirmation that the defect is covered by warranty, at its sole discretion, will either replace or repair the Products at no costs for the customer. Alterations, additions, or repairs not performed by the manufacturer shall negate any warranty. This warranty doesn't cover cosmetic or incidental damages. Shipping costs, taxes, custom fee, any other duties and any costs incurred while removing, reinstalling or troubleshooting the Products, shall be at customer's charge.

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## **Out of warranty repairs**

Products that can not be repaired under warranty as out of the maximum term or that do not work for reasons that would have been covered by warranty, can be repaired at a flat rate as described on the site. For out-of-warranty eligible damages, the repair must be assessed for each individual case.

***Omnia57 RPM-MAP*** - Installation and User Manual,  
Safety Instructions and Warning Booklet

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Date	Revision	Description
02/2019	1.0	First release

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